

Five Fingered Bionic Prosthetic Hand

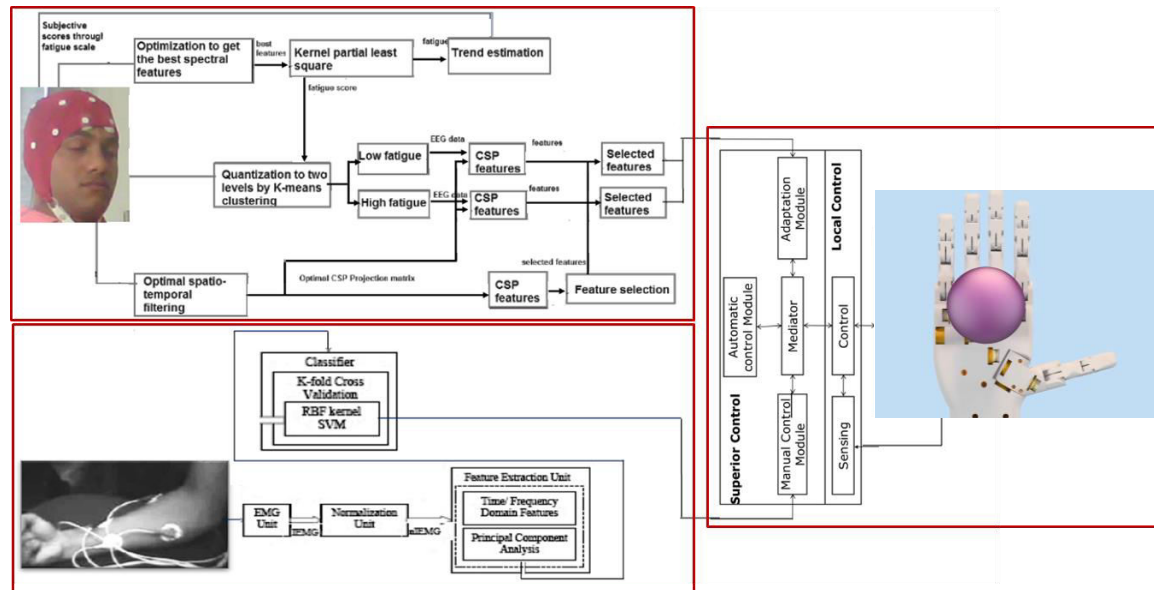
Funding: BDTD, DST

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Objective: Development of a cost-effective anthropomorphic five-fingered bionic prosthetic hand.

Brief Description of Technical/Scientific Achievements

- ❖ Optimization of kinematic design of the **under-actuated hand** using synergies for grasps.
- ❖ Fundamental work on **corticomuscular coupling** – functional coupling between the neural activity in the brain and the associated muscles for an **EEG-EMG Hybrid control**.
- ❖ **Non-assembly mechanism** prosthetic hand i.e., fabricating multi-articulated mechanisms without the involvement of an assembly step.



Bionic Prosthetic Hand